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Lecture 15: Force Densities, Stress Tensors, and Forces

I. Maxwell Stress Tensor

A. Notation

$$\vec{F}_x = \nabla \cdot \vec{\tau}_x, \quad \vec{\tau}_x = T_{xx} \vec{i}_x + T_{xy} \vec{i}_y + T_{xz} \vec{i}_z$$

$$\vec{F}_y = \nabla \cdot \vec{\tau}_y, \quad \vec{\tau}_y = T_{yx} \vec{i}_x + T_{yy} \vec{i}_y + T_{yz} \vec{i}_z$$

$$\vec{F}_z = \nabla \cdot \vec{\tau}_z, \quad \vec{\tau}_z = T_{zx} \vec{i}_x + T_{zy} \vec{i}_y + T_{zz} \vec{i}_z$$

$$\vec{\vec{T}} = \begin{bmatrix} T_{xx} & T_{xy} & T_{xz} \\ T_{yx} & T_{yy} & T_{yz} \\ T_{zx} & T_{zy} & T_{zz} \end{bmatrix}$$

$$\vec{f}_x = \int_V \vec{F}_x dV = \int_V \nabla \cdot \vec{\tau}_x dV = \oint_S \vec{\tau}_x \cdot \vec{n} da = \oint_S [T_{xx}n_x + T_{xy}n_y + T_{xz}n_z] da$$

$$\vec{\tau}_x \cdot \vec{n} = T_{xx}n_x + T_{xy}n_y + T_{xz}n_z = T_{xn}n_n$$

$$\vec{\tau}_y \cdot \vec{n} = T_{yx}n_x + T_{yy}n_y + T_{yz}n_z = T_{yn}n_n$$

$$\vec{\tau}_z \cdot \vec{n} = T_{zx}n_x + T_{zy}n_y + T_{zz}n_z = T_{zn}n_n$$

$$\vec{f}_i = \int_V \nabla \cdot \vec{\tau}_i dV = \oint_S \vec{\tau}_i \cdot \vec{n} dV = \oint_S T_{ij}n_j dS = \int_V F_i dV$$

$$\begin{aligned} \vec{F}_i = \nabla \cdot \vec{\tau}_i &= \frac{\partial}{\partial x} T_{ix} + \frac{\partial}{\partial y} T_{iy} + \frac{\partial}{\partial z} T_{iz} \\ &= \frac{\partial}{\partial x_j} T_{ij} \end{aligned}$$

B. EQS Stress Tensor

$$\vec{F} = \rho_f \vec{E} - \frac{1}{2} \vec{E} \cdot \vec{E} \nabla \varepsilon + \nabla \left(\frac{1}{2} \vec{E} \cdot \vec{E} \frac{\partial \varepsilon}{\partial \rho} \right)$$

$$= \nabla \cdot (\varepsilon \vec{E}) \vec{E} - \frac{1}{2} (\vec{E} \cdot \vec{E}) \nabla \varepsilon + \nabla \left(\frac{1}{2} \vec{E} \cdot \vec{E} \frac{\partial \varepsilon}{\partial \rho} \right)$$

$$F_i = \frac{\partial (\epsilon E_j)}{\partial x_j} E_i - \frac{1}{2} E_k E_k \frac{\partial \epsilon}{\partial x_i} + \frac{\partial}{\partial x_i} \left(\frac{1}{2} E_k E_k \frac{\partial \epsilon}{\partial \rho} \rho \right)$$

$$\nabla \times \bar{E} = 0 \Rightarrow \frac{\partial E_i}{\partial x_j} = \frac{\partial E_j}{\partial x_i}$$

$$F_i = \frac{\partial}{\partial x_j} (\epsilon E_j E_i) - \epsilon E_j \frac{\partial E_i}{\partial x_j} - \frac{1}{2} E_k E_k \frac{\partial \epsilon}{\partial x_i} + \frac{\partial}{\partial x_i} \left(\frac{1}{2} E_k E_k \frac{\partial \epsilon}{\partial \rho} \rho \right)$$

$$F_i = \frac{\partial}{\partial x_j} (\epsilon E_i E_j) - \underbrace{\epsilon E_j \frac{\partial E_j}{\partial x_i}}_{\epsilon \frac{\partial}{\partial x_i} \left(\frac{1}{2} E_j E_j \right)} - \frac{1}{2} E_k E_k \frac{\partial \epsilon}{\partial x_i} + \frac{\partial}{\partial x_i} \left(\frac{1}{2} E_k E_k \frac{\partial \epsilon}{\partial \rho} \rho \right)$$

$$F_i = \frac{\partial}{\partial x_j} (\epsilon E_i E_j) - \frac{\partial}{\partial x_i} \left[\frac{1}{2} \epsilon E_k E_k - \frac{1}{2} \rho \frac{\partial \epsilon}{\partial \rho} E_k E_k \right]$$

$$\frac{\partial}{\partial x_j} = \delta_{ij} \frac{\partial}{\partial x_i}$$

$$\delta_{ij} = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases} \quad \text{Kronecker Delta}$$

$$F_i = \frac{\partial}{\partial x_j} \left[\epsilon E_i E_j - \frac{1}{2} \delta_{ij} E_k E_k \left(\epsilon - \rho \frac{\partial \epsilon}{\partial \rho} \right) \right] = \frac{\partial}{\partial x_j} T_{ij}$$

$$T_{ij} = \epsilon E_i E_j - \frac{1}{2} \delta_{ij} E_k E_k \left(\epsilon - \rho \frac{\partial \epsilon}{\partial \rho} \right)$$

C. MQS Stress Tensor

$$\bar{F} = \bar{J}_f \times \bar{B} - \frac{1}{2} \bar{H} \cdot \bar{H} \nabla \mu + \nabla \left(\frac{1}{2} \rho \frac{\partial \mu}{\partial \rho} \bar{H} \cdot \bar{H} \right)$$

$$= (\nabla \times \bar{H}) \times (\mu \bar{H}) - \frac{1}{2} \bar{H} \cdot \bar{H} \nabla \mu + \nabla \left(\frac{1}{2} \rho \frac{\partial \mu}{\partial \rho} \bar{H} \cdot \bar{H} \right)$$

$$(\nabla \times \bar{H}) \times \bar{H} = (\bar{H} \cdot \nabla) \bar{H} - \frac{1}{2} \nabla (\bar{H} \cdot \bar{H})$$

$$\bar{F} = \mu \left[(\bar{H} \cdot \nabla) \bar{H} - \frac{1}{2} \nabla (\bar{H} \cdot \bar{H}) \right] - \frac{1}{2} \bar{H} \cdot \bar{H} \nabla \mu + \nabla \left(\frac{1}{2} \rho \frac{\partial \mu}{\partial \rho} \bar{H} \cdot \bar{H} \right)$$

$$\begin{aligned}
F_i &= \mu \left[H_j \frac{\partial}{\partial x_j} H_i - \frac{1}{2} \frac{\partial}{\partial x_i} (H_k H_k) \right] - \frac{1}{2} H_k H_k \frac{\partial \mu}{\partial x_i} + \frac{\partial}{\partial x_i} \left(\frac{1}{2} \rho \frac{\partial \mu}{\partial \rho} H_k H_k \right) \\
&= \frac{\partial}{\partial x_j} (\mu H_i H_j) - \underbrace{H_i \frac{\partial}{\partial x_j} (\mu H_j)}_{\nabla \cdot \bar{B} = 0} - \underbrace{\frac{\mu}{2} \frac{\partial}{\partial x_i} H_k H_k - \frac{1}{2} H_k H_k \frac{\partial \mu}{\partial x_i}}_{-\frac{\partial}{\partial x_i} \left(\frac{1}{2} \mu H_k H_k \right)} + \frac{\partial}{\partial x_i} \left(\frac{1}{2} \rho \frac{\partial \mu}{\partial \rho} H_k H_k \right) \\
F_i &= \frac{\partial}{\partial x_j} (\mu H_i H_j) - \frac{\partial}{\partial x_i} \left(\frac{1}{2} \mu H_k H_k - \rho \frac{\partial \mu}{\partial \rho} H_k H_k \right) \\
&= \frac{\partial}{\partial x_j} \left[\mu H_i H_j - \frac{1}{2} \delta_{ij} H_k H_k \left(\mu - \rho \frac{\partial \mu}{\partial \rho} \right) \right] = \frac{\partial}{\partial x_j} T_{ij} \\
T_{ij} &= \mu H_i H_j - \frac{1}{2} \delta_{ij} H_k H_k \left(\mu - \rho \frac{\partial \mu}{\partial \rho} \right)
\end{aligned}$$

II. Air-Gap Magnetic Machines

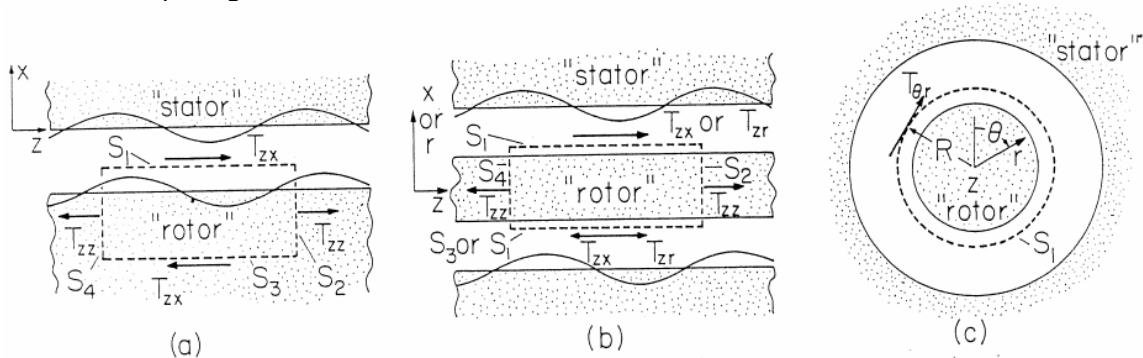
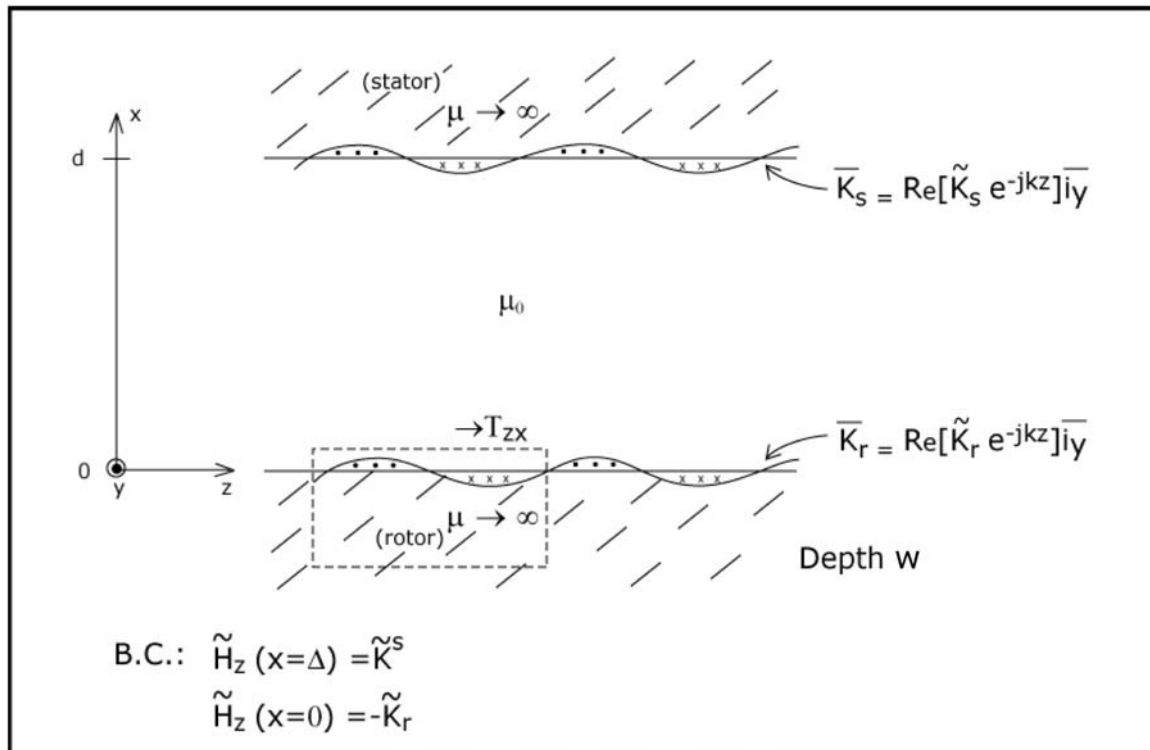


Fig. 4.2.1. Typical "air-gap" configurations in which a force or torque on a rigid "rotor" results from spatially periodic sources interacting with spatially periodic excitations on a rigid "stator." Because of the periodicity, the force or torque can be represented in terms of the electric or magnetic stress acting at the air-gap surfaces S_1 : (a) planar geometry or developed model; (b) planar or cylindrical beam; (c) cylindrical rotor.

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A. Generalized Description



$$f_z = \oint_S T_{zx} n_x dz dy = w \int_0^{2\pi/k} \mu_0 H_z H_x \Big|_{x=0} dz = w \int_0^{2\pi/k} \mu_0 H_z^r H_x^r dz$$

force on a wavelength

$$a(z, t) = \text{Re}[\tilde{A} e^{-jkz}], \quad b(z, t) = \text{Re}[\tilde{B} e^{-jkz}]$$

$$\frac{k}{2\pi} \int_0^{2\pi/k} a(z, t) b(z, t) dz = \frac{1}{2} \text{Re}[\tilde{A} \tilde{B}^*] = \frac{1}{2} \text{Re}[\tilde{A}^* \tilde{B}]$$

$$f_z = \frac{2\pi w \mu_0}{k} \text{Re}[\tilde{H}_z^r \tilde{H}_x^{r*}]$$

$$= \frac{2\pi w \mu_0}{k} \text{Re}[-\tilde{K}_r \tilde{H}_x^{r*}]$$

$$\begin{bmatrix} \tilde{B}_x^s \\ \tilde{B}_x^r \end{bmatrix} = \mu_0 k \begin{bmatrix} -\coth kd & \frac{1}{\sinh kd} \\ \frac{1}{\sinh kd} & \coth kd \end{bmatrix} \begin{bmatrix} \tilde{\chi}_s \\ \tilde{\chi}_r \end{bmatrix}$$

$$\tilde{H}_z = +jk\tilde{\chi} \Rightarrow \tilde{\chi}^s = \frac{1}{jk}\tilde{H}_z^s = \frac{\tilde{K}^s}{jk}$$

$$\tilde{\chi}^r = \frac{\tilde{H}_z^r}{jk} = -\frac{\tilde{K}_r^r}{jk}$$

$$\mu_0\tilde{H}_x^r = \mu_0k \left[\frac{-\tilde{\chi}^s}{\sinh kd} + \tilde{\chi}^r \coth kd \right]$$

$$= \mu_0k \left[\frac{-\tilde{K}^s}{jk \sinh kd} - \frac{\tilde{K}_r^r}{jk} \coth kd \right]$$

$$\text{Re} \left[-\tilde{K}_r^* \tilde{H}_x^r \mu_0 \right] = -\text{Re} \left[\frac{+j\mu_0 K}{K} \left(\frac{\tilde{K}_r^* \tilde{K}^s}{\sinh kd} + \tilde{K}_r^* \tilde{K}_r \coth kd \right) \right]$$

$$= \text{Re} \left[-\mu_0 j \tilde{K}_r^* \tilde{K}_s^s / \sinh kd \right]$$

$$f_z = -\frac{\pi W}{k} \frac{\mu_0}{\sinh kd} \text{Re} \left[j \tilde{K}_r^* \tilde{K}_s \right] \text{ (force on each wavelength)}$$

B. Synchronous Interaction

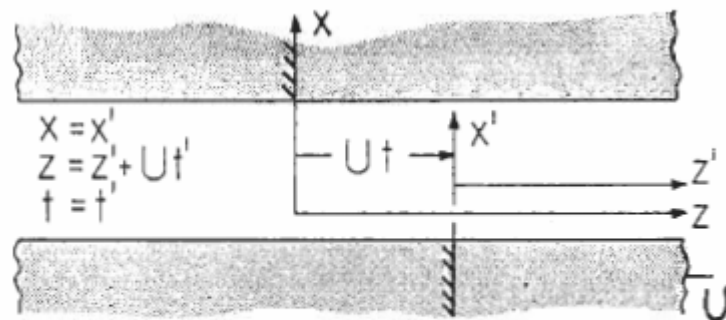


Fig. 4.3.1. Rotor and stator reference frames z' and z .

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$$K^s = K_0^s \sin[\omega_s t - kz] = \text{Re} \left[-jK_0^s e^{j(\omega_s t - kz)} \right]$$

$$K^r = K_0^r \sin[\omega_r t - k(z' - \delta)]; \quad z' = z - Ut$$

$$= K_0^r \sin[(\omega_r + kU)t - k(z - \delta)]$$

$$= \text{Re} \left[-jK_0^r e^{j(\omega_r + kU)t} e^{jk\delta} \right]$$

$$\tilde{K}^s = -jK_0^s e^{j\omega_s t}$$

$$\tilde{K}^r = -jK_0^r e^{jk\delta} e^{j(\omega_r + kU)t}$$

$$f_z = -\frac{\pi W}{k} \frac{\mu_0}{\sinh kd} \text{Re} \left[j(-jK_0^s) e^{j\omega_s t} (jK_0^r e^{-jk\delta}) e^{-j(\omega_r + kU)t} \right]$$

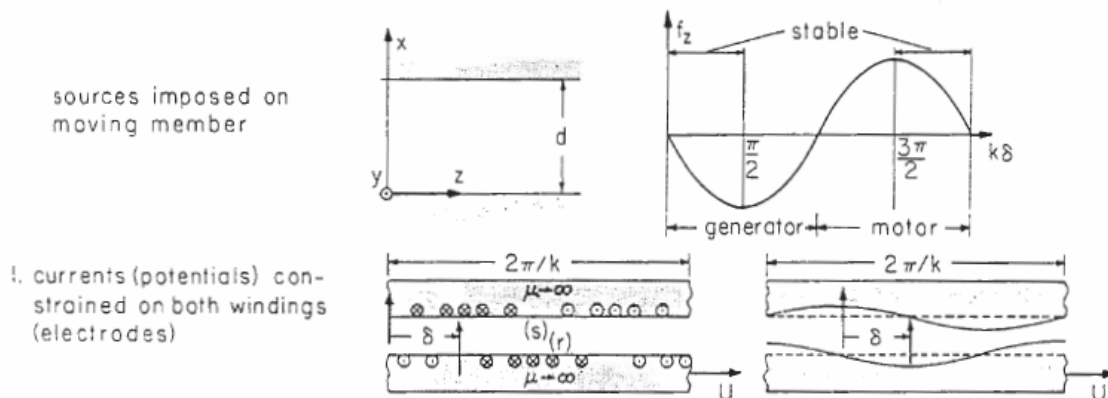
$$= -\frac{\pi W}{k} \frac{\mu_0}{\sinh kd} K_0^s K_0^r \text{Re} \left[j e^{-jk\delta} e^{j(\omega_s - \omega_r - kU)t} \right]$$

For time average force $\Rightarrow \omega_s = \omega_r + kU$ (synchronous condition)

Usually $\omega_r = 0 \Rightarrow \omega_s = kU$

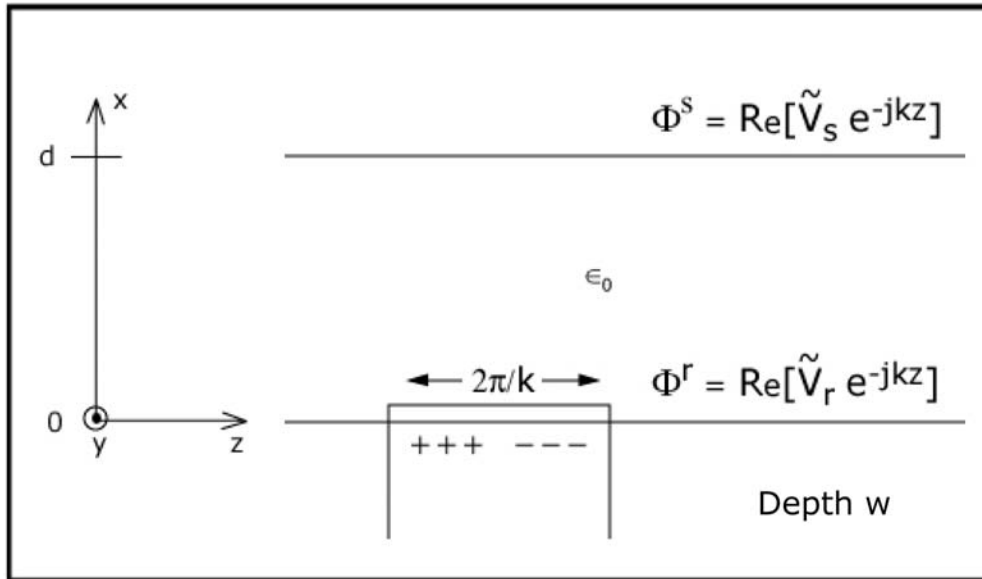
$$\langle f_z \rangle = -\frac{\pi W}{k} \frac{\mu_0}{\sinh kd} K_0^s K_0^r \sin k\delta$$

Table 4.3.1. Basic configurations illustrating classes of electromechanical interactions and devices. MQS and EQS systems respectively in left and right columns.



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III. Electrostatic Machine



$$f_z = \frac{w2\pi}{k} \int_0^{2\pi/k} T_{zx} \Big|_{x=0} dz = \frac{2\pi w}{k} \int_0^{2\pi/k} \epsilon_0 E_z E_x \Big|_{x=0}$$

$$\tilde{E}_z^r = jk\tilde{V}_r$$

$$f_z = \frac{1}{2} \frac{2\pi w}{k} \text{Re} \left[\epsilon_0 \tilde{E}_z^r \tilde{E}_x^r \right]$$

$$= \frac{\pi w}{k} \text{Re} \left[\epsilon_0 (-jk\tilde{V}_r^*) \tilde{E}_x^r \right]$$

$$\begin{bmatrix} \tilde{D}_x^s \\ \tilde{D}_x^r \end{bmatrix} = \epsilon_0 k \begin{bmatrix} -\coth kd & \frac{1}{\sinh kd} \\ -\frac{1}{\sinh kd} & \coth kd \end{bmatrix} \begin{bmatrix} \tilde{V}_s \\ \tilde{V}_r \end{bmatrix}$$

$$\epsilon_0 \tilde{E}_x^r = \epsilon_0 k \left[\frac{-\tilde{V}_s}{\sinh kd} + \tilde{V}_r \coth kd \right]$$

$$\text{Re} \left[-jk\epsilon_0 \tilde{V}_r^* \tilde{E}_x^r \right] = \text{Re} \left[-jk^2 \epsilon_0 \tilde{V}_r^* \left(\frac{-\tilde{V}_s}{\sinh kd} + \tilde{V}_r \coth kd \right) \right]$$

$$= \text{Re} \left[+jk^2 \epsilon_0 \tilde{V}_s \tilde{V}_r^* / \sinh kd \right]$$

$$f_z = \frac{\pi W}{\kappa} \frac{k^2 \epsilon_0}{\sinh kd} \operatorname{Re} \left[j \tilde{V}_s \tilde{V}_r^* \right]$$

$$V_s = V_0^s \cos(\omega_s t - kz)$$

$$V_r = -V_0^r \cos(\omega_r t - k(z' - \delta)); z' = z - Ut$$

$$\tilde{V}^r = -V_0^r e^{j(\omega_r + kU)t} e^{jk\delta}$$

$$\tilde{V}^s = V_0^s e^{j\omega_s t}$$

$$\langle f_z \rangle = \frac{\pi W k \epsilon_0}{\sinh kd} \operatorname{Re} \left[-j V_0^s V_0^r e^{-jk\delta} e^{j(\omega_s - \omega_r - kU)t} \right]$$

$$\omega_s = \omega_r + kU$$

$$\langle f_z \rangle = -\frac{\pi W k \epsilon_0}{\sinh kd} V_0^s V_0^r \sin k\delta$$

IV. Derivation of the Korteweg-Helmholtz Force Density for Incompressible Media from the Quasistatic Poynting's Theorem

A. Poynting's Theorem

$$\nabla \times \bar{\mathbf{E}} = -\frac{\partial \bar{\mathbf{B}}}{\partial t}$$

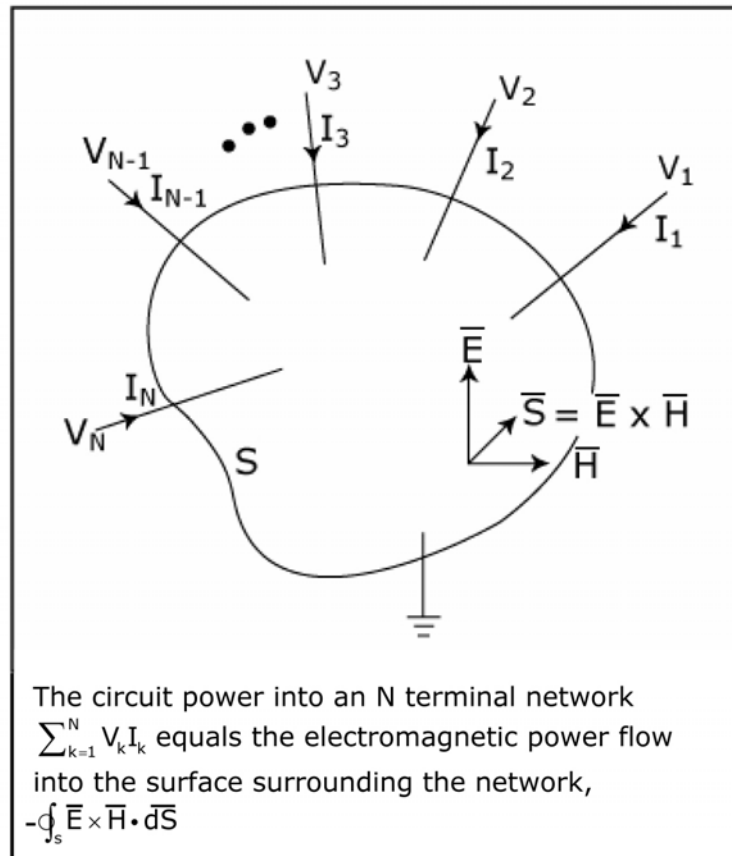
$$\nabla \times \bar{\mathbf{H}} = \bar{\mathbf{J}}_f + \frac{\partial \bar{\mathbf{D}}}{\partial t}$$

$$\nabla \cdot \bar{\mathbf{D}} = \rho_f$$

$$\nabla \cdot \bar{\mathbf{B}} = 0$$

$$\begin{aligned} \nabla \cdot (\bar{\mathbf{E}} \times \bar{\mathbf{H}}) &= \bar{\mathbf{H}} \cdot (\nabla \times \bar{\mathbf{E}}) - \bar{\mathbf{E}} \cdot (\nabla \times \bar{\mathbf{H}}) \\ &= -\bar{\mathbf{H}} \cdot \frac{\partial \bar{\mathbf{B}}}{\partial t} - \bar{\mathbf{E}} \cdot \frac{\partial \bar{\mathbf{D}}}{\partial t} - \bar{\mathbf{E}} \cdot \bar{\mathbf{J}}_f \end{aligned}$$

B. Power In Quasistatic Electric Circuits



Far away from the circuit elements

$$\nabla \times \vec{E} = 0 \Rightarrow \vec{E} = -\nabla \Phi$$

$$\nabla \times \vec{H} = \vec{J}_f \Rightarrow \nabla \cdot \vec{J}_f = 0$$

$$P_{in} = -\oint_S (\vec{E} \times \vec{H}) \cdot d\vec{a}$$

$$= +\oint_S (\nabla \Phi \times \vec{H}) \cdot d\vec{a}$$

$$= \int_V \nabla \cdot (\nabla \Phi \times \vec{H}) dV$$

$$\nabla \cdot (\nabla \Phi \times \vec{H}) = \vec{H} \cdot \nabla \times (\nabla \Phi) - \nabla \Phi \cdot (\nabla \times \vec{H})$$

$$= -\vec{J}_f \cdot \nabla \Phi = -\nabla \cdot (\vec{J}_f \Phi)$$

$$\begin{aligned}
P_{\text{in}} &= -\int_V \nabla \cdot (\bar{\mathbf{J}}_f \Phi) dV \\
&= -\oint_S \bar{\mathbf{J}}_f \Phi \cdot \bar{d\mathbf{a}} \\
&= -\sum_{k=1}^N V_k \underbrace{\oint_S \bar{\mathbf{J}}_f \cdot \bar{d\mathbf{a}}}_{-I_k} \\
&= \sum_{k=1}^N V_k I_k
\end{aligned}$$

C. Electroquasistatics (EQS)

$$\text{Ohmic Media: } \bar{\mathbf{J}}_f' = \sigma \bar{\mathbf{E}}' = \bar{\mathbf{J}}_f - \rho_f \bar{\mathbf{v}} \Rightarrow \bar{\mathbf{J}}_f = \sigma \bar{\mathbf{E}} + \rho_f \bar{\mathbf{v}}$$

$$\bar{\mathbf{D}} = \varepsilon(\mathbf{x}, \mathbf{y}, \mathbf{z}) \bar{\mathbf{E}}$$

$$\begin{aligned}
\int_V \nabla \cdot (\bar{\mathbf{E}} \times \bar{\mathbf{H}}) dV &= \oint_S \bar{\mathbf{E}} \times \bar{\mathbf{H}} \cdot \bar{d\mathbf{a}} = -\sum_k V_k I_k = -\int_V \bar{\mathbf{E}} \cdot \frac{\partial}{\partial t} (\varepsilon(\mathbf{x}, \mathbf{y}, \mathbf{z}) \bar{\mathbf{E}}) dV \\
&\quad - \int_V \bar{\mathbf{E}} \cdot (\sigma \bar{\mathbf{E}} + \rho_f \bar{\mathbf{v}}) dV
\end{aligned}$$

$$\begin{aligned}
\sum_k V_k I_k &= \int_V \frac{\varepsilon(\mathbf{x}, \mathbf{y}, \mathbf{z}) \bar{\mathbf{E}}}{\varepsilon(\mathbf{x}, \mathbf{y}, \mathbf{z})} \cdot \frac{\partial}{\partial t} (\varepsilon(\mathbf{x}, \mathbf{y}, \mathbf{z}) \bar{\mathbf{E}}) dV + \int_V \sigma |\bar{\mathbf{E}}|^2 dV + \int_V \rho_f \bar{\mathbf{E}} \cdot \bar{\mathbf{v}} dV \\
&= \int_V \frac{1}{2} \frac{1}{\varepsilon(\mathbf{x}, \mathbf{y}, \mathbf{z})} \frac{\partial}{\partial t} [\varepsilon^2(\mathbf{x}, \mathbf{y}, \mathbf{z}) |\bar{\mathbf{E}}|^2] dV + \int_V \sigma |\bar{\mathbf{E}}|^2 dV + \int_V \rho_f \bar{\mathbf{E}} \cdot \bar{\mathbf{v}} dV
\end{aligned}$$

$$\int_V \frac{1}{2\varepsilon(\mathbf{x}, \mathbf{y}, \mathbf{z})} \frac{\partial}{\partial t} [\varepsilon^2(\mathbf{x}, \mathbf{y}, \mathbf{z}) |\bar{\mathbf{E}}|^2] dV = \int_V \frac{\partial}{\partial t} \left[\frac{\cancel{\varepsilon}^2(\mathbf{x}, \mathbf{y}, \mathbf{z}) |\bar{\mathbf{E}}|^2}{2\varepsilon(\mathbf{x}, \mathbf{y}, \mathbf{z})} \right] dV$$

$$-\int_V \frac{\varepsilon^2(\mathbf{x}, \mathbf{y}, \mathbf{z}) |\bar{\mathbf{E}}|^2}{2} \frac{\partial}{\partial t} \left(\frac{1}{\varepsilon(\mathbf{x}, \mathbf{y}, \mathbf{z})} \right) dV$$

$$= \int_V \frac{\partial}{\partial t} \left[\frac{1}{2} \varepsilon(\mathbf{x}, \mathbf{y}, \mathbf{z}) |\bar{\mathbf{E}}|^2 \right] dV + \int_V \frac{|\bar{\mathbf{E}}|^2}{2} \frac{\partial}{\partial t} (\varepsilon(\mathbf{x}, \mathbf{y}, \mathbf{z})) dV$$

Theorem: $\frac{d}{dt} \int_V \alpha dV = \int_V \frac{\partial \alpha}{\partial t} dV + \int_V \nabla \cdot (\alpha \bar{v}) dV$

Conservation of mass: $\alpha = \rho$ mass density

$$\frac{d}{dt} \int_V \rho dV = 0 = \int_V \frac{\partial \rho}{\partial t} dV + \int_V \nabla \cdot (\rho \bar{v}) dV$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \bar{v}) = 0 = \frac{\partial \rho}{\partial t} + (\bar{v} \cdot \nabla) \rho + \rho (\nabla \cdot \bar{v}) = 0$$

Incompressible: $\frac{d\rho}{dt} = \frac{\partial \rho}{\partial t} + (\bar{v} \cdot \nabla) \rho = 0 \Rightarrow \nabla \cdot \bar{v} = 0$

$$\frac{d}{dt} \int_V \varepsilon dV = \int_V \frac{\partial \varepsilon}{\partial t} dV + \int_V \nabla \cdot (\varepsilon \bar{v}) dV = 0$$

$$\frac{\partial \varepsilon}{\partial t} + \nabla \cdot (\varepsilon \bar{v}) = \frac{\partial \varepsilon}{\partial t} + (\bar{v} \cdot \nabla) \varepsilon + \varepsilon \nabla \cdot \bar{v} = 0$$

$$\frac{\partial \varepsilon}{\partial t} = -(\bar{v} \cdot \nabla) \varepsilon$$

$$\int_V \frac{1}{2\varepsilon(x,y,z)} \frac{\partial}{\partial t} \left[\varepsilon^2(x,y,z) |\bar{E}|^2 \right] dV = \int_V \frac{\partial}{\partial t} \left[\frac{1}{2} \varepsilon(x,y,z) |\bar{E}|^2 \right] dV + \int_V \frac{|\bar{E}|^2}{2} (-\bar{v} \cdot \nabla) \varepsilon(x,y,z) dV$$

$$\sum_k V_k I_k = \underbrace{\int_V \frac{\partial}{\partial t} \left[\frac{1}{2} \varepsilon(x,y,z) |\bar{E}|^2 \right] dV}_{\text{Energy Stored (} W_E \text{) Rate}} + \underbrace{\int_V \sigma |\bar{E}|^2 dV}_{\text{Power Dissipated } P_E} + \underbrace{\int_V \left[\rho_f \bar{E} - \frac{1}{2} |\bar{E}|^2 \nabla \varepsilon \right] \cdot \bar{v} dV}_{\text{Force Density}}$$

Work Rate = Mechanical Power

$$\bar{F} = \rho_f \bar{E} - \frac{1}{2} |\bar{E}|^2 \nabla \varepsilon \quad (\text{force per unit volume})$$

nt/m³

$$\vec{f} = \int_V \vec{F} dV$$

↑
force (nts)

D. Magnetoquasistatics

$$\vec{J}' = \vec{J}_f, \vec{E}' = \vec{E} + \vec{v} \times \vec{B} \Rightarrow \vec{J}' = \vec{J}_f = \sigma \vec{E}' = \sigma (\vec{E} + \vec{v} \times \vec{B})$$

$$\vec{B} = \mu(x, y, z) \vec{H}$$

$$\int_V \nabla \cdot (\vec{E} \times \vec{H}) dV = \oint_S \vec{E} \times \vec{H} \cdot d\vec{a} = -\sum_k V_k I_k = -\int_V \vec{H} \cdot \frac{\partial}{\partial t} (\mu(x, y, z) \vec{H}) dV$$

$$-\int_V [\vec{E}' - \vec{v} \times \vec{B}] \cdot \vec{J}_f dV$$

$$P_{\text{dissipated}} = \int_V \vec{E}' \cdot \vec{J}'_f dV = \int_V \vec{E}' \cdot \vec{J}_f dV$$

$$\vec{J}_f \cdot (\vec{v} \times \vec{B}) = -\vec{J}_f \cdot (\vec{B} \times \vec{v}) = -(\vec{J}_f \times \vec{B}) \cdot \vec{v}$$

$$\vec{H} \cdot \frac{\partial}{\partial t} [\mu(x, y, z) \vec{H}] = \frac{\mu(x, y, z) \vec{H}}{\mu(x, y, z)} \frac{\partial}{\partial t} [\mu(x, y, z) \vec{H}]$$

$$= \frac{1}{\mu(x, y, z)} \frac{\partial}{\partial t} \left[\frac{1}{2} \mu^2(x, y, z) |\vec{H}|^2 \right]$$

$$= \frac{\partial}{\partial t} \left[\frac{1}{2} \frac{\mu^2(x, y, z) |\vec{H}|^2}{\mu(x, y, z)} \right] - \frac{1}{2} \mu^2(x, y, z) |\vec{H}|^2 \frac{\partial}{\partial t} \left[\frac{1}{\mu(x, y, z)} \right]$$

$$= \frac{\partial}{\partial t} \left[\frac{1}{2} \mu(x, y, z) |\vec{H}|^2 \right] + \frac{1}{2} \frac{\mu^2(x, y, z) |\vec{H}|^2}{\mu^2(x, y, z)} \frac{\partial}{\partial t} [\mu(x, y, z)]$$

$$\frac{d}{dt} \int_V \mu dV = 0 \Rightarrow \frac{\partial \mu}{\partial t} + (\vec{v} \cdot \nabla) \mu = 0 \quad (\nabla \cdot \vec{v} = 0)$$

$$\vec{H} \cdot \frac{\partial}{\partial t} [\mu(x, y, z) \vec{H}] = \frac{\partial}{\partial t} \left[\frac{1}{2} \mu(x, y, z) |\vec{H}|^2 \right] - \frac{1}{2} |\vec{H}|^2 \nabla \mu \cdot \vec{v}$$

$$\sum_k V_k I_k = \int_V \underbrace{\frac{\partial}{\partial t} \left[\frac{1}{2} \mu(x, y, z) |\bar{H}|^2 \right]}_{\text{Energy density } W_M} dV + P_{\text{dissipated}}$$

$$+ \int_V \bar{v} \cdot \underbrace{\left[\bar{J}_f \times \bar{B} - \frac{1}{2} |\bar{H}|^2 \nabla \mu \right]}_{\bar{F}_M = \text{force density}} dV$$

Mechanical Power

$$W_M = \int_V \underbrace{\frac{1}{2} \mu(x, y, z) |\bar{H}|^2}_{\text{Total Magnetic Energy}} dV, \quad P_{\text{dissipated}} = \int_V \bar{E}' \cdot \bar{J}_f dV = \int_V \bar{E}' \cdot \bar{J}_f' dV = \int_V \sigma |\bar{E}'|^2 dV$$

$$\bar{F}_M = \bar{J}_f \times \bar{B} - \frac{1}{2} |\bar{H}|^2 \nabla \mu \quad \text{force density}$$

V. Compressible Media

A. Electroquasistatics (EQS)

$$\text{Ohmic media: } \bar{J}' = \sigma \bar{E}'$$

Polarization dependent on mass density (ρ) alone, electrically linear

$$\bar{D} = \epsilon(\rho) \bar{E}$$

$$\text{EQS Galilean Transformation: } \bar{J} = \sigma \bar{E} + \rho_f \bar{v}$$

$$\int_V \nabla \cdot (\bar{E} \times \bar{H}) dV = \oint_S \bar{E} \times \bar{H} \cdot \bar{d}\mathbf{a} = -\sum_k V_k I_k = -\int_V \bar{E} \cdot \frac{\partial}{\partial t} [\epsilon(\rho) \bar{E}] dV$$

$$-\int_V \bar{E} \cdot (\sigma \bar{E} + \rho_f \bar{v}) dV$$

$$\bar{E} \cdot \frac{\partial}{\partial t} [\epsilon(\rho) \bar{E}] = \frac{\epsilon(\rho) \bar{E}}{\epsilon(\rho)} \cdot \frac{\partial}{\partial t} [\epsilon(\rho) \bar{E}] = \frac{1}{\epsilon(\rho)} \frac{\partial}{\partial t} \left[\frac{1}{2} \epsilon^2(\rho) |\bar{E}|^2 \right]$$

$$= \frac{\partial}{\partial t} \left[\frac{1}{2} \frac{\varepsilon^2(\rho)}{\varepsilon(\rho)} |\bar{\mathbf{E}}|^2 \right] - \frac{\varepsilon^2(\rho) |\bar{\mathbf{E}}|^2}{2} \frac{\partial}{\partial t} \left(\frac{1}{\varepsilon(\rho)} \right)$$

$$\begin{aligned} \bar{\mathbf{E}} \cdot \frac{\partial}{\partial t} [\varepsilon(\rho) \bar{\mathbf{E}}] &= \frac{\partial}{\partial t} \left[\frac{1}{2} \varepsilon(\rho) |\bar{\mathbf{E}}|^2 \right] + \frac{\cancel{\varepsilon^2(\rho)} |\bar{\mathbf{E}}|^2}{2} \left(\frac{+1}{\cancel{\varepsilon^2(\rho)}} \frac{\partial \varepsilon(\rho)}{\partial t} \right) \\ &= \frac{\partial}{\partial t} \left[\frac{1}{2} \varepsilon(\rho) |\bar{\mathbf{E}}|^2 \right] + \frac{1}{2} |\bar{\mathbf{E}}|^2 \frac{\partial \varepsilon(\rho)}{\partial t} \end{aligned}$$

$$\frac{\partial \varepsilon(\rho)}{\partial t} = \frac{\partial \varepsilon(\rho)}{\partial \rho} \frac{\partial \rho}{\partial t} ; \quad \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \bar{\mathbf{v}}) = 0 \quad (\text{Conservation of mass})$$

$$\frac{\partial \varepsilon(\rho)}{\partial t} = \frac{\partial \varepsilon(\rho)}{\partial \rho} (-\nabla \cdot (\rho \bar{\mathbf{v}}))$$

$$\begin{aligned} -\sum_k \mathbf{v}_k \cdot \mathbf{I}_k &= -\int_V \frac{\partial}{\partial t} \left[\frac{1}{2} \varepsilon(\rho) |\bar{\mathbf{E}}|^2 \right] dV - \int_V \frac{1}{2} |\bar{\mathbf{E}}|^2 \frac{\partial \varepsilon(\rho)}{\partial t} dV \\ &\quad - \int_V \sigma |\bar{\mathbf{E}}|^2 dV - \int_V \rho_f \bar{\mathbf{E}} \cdot \bar{\mathbf{v}} dV \end{aligned}$$

$$\begin{aligned} \int_V \frac{1}{2} |\bar{\mathbf{E}}|^2 \frac{\partial \varepsilon(\rho)}{\partial t} dV &= -\int_V \frac{1}{2} |\bar{\mathbf{E}}|^2 \frac{\partial \varepsilon}{\partial \rho} \nabla \cdot (\rho \bar{\mathbf{v}}) dV \\ &= -\int_V \nabla \cdot \left[\frac{1}{2} \frac{\partial \varepsilon}{\partial \rho} |\bar{\mathbf{E}}|^2 \rho \bar{\mathbf{v}} \right] dV + \int_V \rho \bar{\mathbf{v}} \cdot \nabla \left[\frac{1}{2} |\bar{\mathbf{E}}|^2 \frac{\partial \varepsilon}{\partial \rho} \right] dV \\ &= -\oint_S \frac{1}{2} \rho \frac{\partial \varepsilon}{\partial \rho} |\bar{\mathbf{E}}|^2 \bar{\mathbf{v}} \cdot \bar{\mathbf{n}} da + \int_V \bar{\mathbf{v}} \cdot \left\{ \nabla \left[\frac{1}{2} \rho \frac{\partial \varepsilon}{\partial \rho} |\bar{\mathbf{E}}|^2 \right] - \frac{1}{2} |\bar{\mathbf{E}}|^2 \frac{\partial \varepsilon}{\partial \rho} \nabla \rho \right\} dV \end{aligned}$$

$$\begin{aligned} \sum_k \mathbf{v}_k \cdot \mathbf{I}_k &= \int_V \frac{\partial}{\partial t} \left[\frac{1}{2} \varepsilon(\rho) |\bar{\mathbf{E}}|^2 \right] dV + \int_V \sigma |\bar{\mathbf{E}}|^2 dV \\ &\quad - \oint_S \frac{1}{2} \rho \frac{\partial \varepsilon}{\partial \rho} |\bar{\mathbf{E}}|^2 \bar{\mathbf{v}} \cdot \bar{\mathbf{n}} da \\ &\quad + \int_V \bar{\mathbf{v}} \cdot \left[\rho_f \bar{\mathbf{E}} - \frac{1}{2} |\bar{\mathbf{E}}|^2 \nabla \varepsilon + \nabla \left[\frac{1}{2} \rho \frac{\partial \varepsilon}{\partial \rho} |\bar{\mathbf{E}}|^2 \right] \right] dV \end{aligned}$$

where

$$\frac{\partial \varepsilon}{\partial \rho} \nabla \rho = \nabla \varepsilon$$

electric energy

$$W_E = \int_V \frac{1}{2} \varepsilon(\rho) |\bar{E}|^2 dV, \quad P_{\text{dissipated}} = \int_V \sigma |\bar{E}|^2 dV \quad (\text{power dissipated})$$

$$\bar{F}_E = \rho_f \bar{E} - \frac{1}{2} |\bar{E}|^2 \nabla \varepsilon + \nabla \left[\frac{1}{2} \rho \frac{\partial \varepsilon}{\partial \rho} |\bar{E}|^2 \right] \quad \text{force density}$$

$$\oint_S \frac{1}{2} \rho \frac{\partial \varepsilon}{\partial \rho} |\bar{E}|^2 \bar{v} \cdot \bar{n} da = 0 \quad \text{because as } S \rightarrow \infty, |\bar{E}|^2 da \rightarrow 0$$

$$\sum_k V_k I_k = \frac{\partial W_E}{\partial t} + P_{\text{dissipated}} + \underbrace{\int_V \bar{F}_E \cdot \bar{v} dV}_{\text{Mechanical Power}}$$

B. Magnetoquasistatics (MQS)

$$\text{MQS Galilean Transformation: } \bar{J}_f' = \bar{J}_f, \quad \bar{E}' = \bar{E} + \bar{v} \times \bar{B}$$

$$\bar{B} = \mu(\rho) \bar{H}$$

$$\begin{aligned} \int_V \nabla \cdot (\bar{E} \times \bar{H}) dV &= \oint_S \bar{E} \times \bar{H} \cdot \bar{da} = -\sum_k V_k I_k = -\int_V \bar{H} \cdot \frac{\partial}{\partial t} [\mu(\rho) \bar{H}] dV \\ &\quad - \int_V [\bar{E}' - \bar{v} \times \bar{B}] \cdot \bar{J}_f dV \end{aligned}$$

$$P_{\text{dissipated}} = \int_V \bar{E}' \cdot \bar{J}_f' dV = \int_V \bar{E}' \cdot \bar{J}_f dV$$

$$\bar{J}_f \cdot (\bar{v} \times \bar{B}) = -\bar{J}_f \cdot (\bar{B} \times \bar{v}) = -(\bar{J}_f \times \bar{B}) \cdot \bar{v}$$

$$\begin{aligned} \bar{H} \cdot \frac{\partial}{\partial t} [\mu(\rho) \bar{H}] &= \frac{\mu(\rho) \bar{H}}{\mu(\rho)} \cdot \frac{\partial}{\partial t} [\mu(\rho) \bar{H}] = \frac{1}{\mu(\rho)} \frac{\partial}{\partial t} \left[\frac{1}{2} \mu^2(\rho) |\bar{H}|^2 \right] \\ &= \frac{\partial}{\partial t} \left[\frac{1}{2} \frac{\mu^2(\rho)}{\mu(\rho)} |\bar{H}|^2 \right] - \frac{1}{2} \mu^2(\rho) |\bar{H}|^2 \frac{\partial}{\partial t} \left[\frac{1}{\mu(\rho)} \right] \end{aligned}$$

$$\begin{aligned}
&= \frac{\partial}{\partial t} \left[\frac{1}{2} \mu(\rho) |\vec{H}|^2 \right] + \frac{1}{2} \frac{\mu^2(\rho)}{\mu^2(\rho)} |\vec{H}|^2 \frac{\partial \mu(\rho)}{\partial t} \\
&= \frac{\partial}{\partial t} \left[\frac{1}{2} \mu(\rho) |\vec{H}|^2 \right] + \frac{1}{2} |\vec{H}|^2 \frac{\partial \mu(\rho)}{\partial t}
\end{aligned}$$

$$\frac{d}{dt} \int_{\bar{V}} \mu(\rho) dV = 0 \Rightarrow \frac{\partial \mu(\rho)}{\partial t} + \nabla \cdot [\mu(\rho) \bar{v}] = 0$$

$$\frac{\partial \mu(\rho)}{\partial t} = \frac{\partial \mu(\rho)}{\partial \rho} \frac{\partial \rho}{\partial t} ; \quad \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \bar{v}) = 0$$

$$\frac{\partial \mu(\rho)}{\partial t} = \frac{\partial \mu(\rho)}{\partial \rho} (-\nabla \cdot (\rho \bar{v}))$$

$$\begin{aligned}
-\sum_k \mathbf{V}_k \mathbf{I}_k &= -\int_{\bar{V}} \frac{\partial}{\partial t} \left[\frac{1}{2} \mu(\rho) |\vec{H}|^2 \right] dV - \int_{\bar{V}} \frac{1}{2} |\vec{H}|^2 \frac{\partial \mu(\rho)}{\partial t} dV - P_{\text{diss}} \\
&\quad - \int_{\bar{V}} (\vec{J}_f \times \vec{B}) \cdot \bar{v} dV
\end{aligned}$$

$$\int_{\bar{V}} \frac{1}{2} |\vec{H}|^2 \frac{\partial \mu(\rho)}{\partial t} dV = -\int_{\bar{V}} \frac{1}{2} |\vec{H}|^2 \frac{\partial \mu}{\partial \rho} \nabla \cdot (\rho \bar{v}) dV$$

$$= -\int_{\bar{V}} \nabla \cdot \left[\frac{1}{2} \frac{\partial \mu}{\partial \rho} |\vec{H}|^2 \rho \bar{v} \right] dV + \int_{\bar{V}} \rho \bar{v} \cdot \nabla \left[\frac{1}{2} |\vec{H}|^2 \frac{\partial \mu}{\partial \rho} \right] dV$$

$$= -\oint_S \frac{1}{2} \rho \frac{\partial \mu}{\partial \rho} |\vec{H}|^2 \bar{v} \cdot \bar{n} da + \int_{\bar{V}} \bar{v} \cdot \left\{ \nabla \left[\frac{1}{2} \rho \frac{\partial \mu}{\partial \rho} |\vec{H}|^2 \right] - \frac{1}{2} |\vec{H}|^2 \frac{\partial \mu}{\partial \rho} \nabla \rho \right\} dV$$


$$\sum_k \mathbf{V}_k \mathbf{I}_k = \int_{\bar{V}} \frac{\partial}{\partial t} \left[\frac{1}{2} \mu(\rho) |\vec{H}|^2 \right] dV + P_{\text{diss}} - \oint_S \frac{1}{2} \rho \frac{\partial \mu}{\partial \rho} |\vec{H}|^2 \bar{v} \cdot \bar{n} da$$

$$+ \int_{\bar{V}} \bar{v} \cdot \left[\vec{J}_f \times \vec{B} - \frac{1}{2} |\vec{H}|^2 \nabla \mu + \nabla \left(\frac{1}{2} \rho \frac{\partial \mu}{\partial \rho} |\vec{H}|^2 \right) \right] dV$$

where

$$\frac{\partial \mu}{\partial \rho} \nabla \rho = \nabla \mu$$

$$W_M = \int_V \frac{1}{2} \mu(\rho) |\vec{H}|^2 dV, \quad P_{\text{dissipated}} = \int_V \vec{E}' \cdot \vec{J}'_f dV = \int_V \vec{E}' \cdot \vec{J}_f dV \quad \text{Power dissipated}$$


 magnetic energy

$$\vec{F}_M = \vec{J}_f \times \vec{B} - \frac{1}{2} |\vec{H}|^2 \nabla \mu + \nabla \left(\frac{1}{2} \rho \frac{\partial \mu}{\partial \rho} |\vec{H}|^2 \right) \quad \text{force density}$$

$$\oint_S \frac{1}{2} \rho \frac{\partial \mu}{\partial \rho} |\vec{H}|^2 \vec{v} \cdot \vec{n} da = 0 \quad \text{because as } S \rightarrow \infty, |\vec{H}|^2 da \rightarrow 0$$

$$\sum_k V_k I_k = \frac{\partial W_M}{\partial t} + P_{\text{dissipated}} + \underbrace{\int_V \vec{F}_M \cdot \vec{v} dV}_{\text{Mechanical Power}}$$

C. Conclusions

Force densities

$$\text{EQS: } \vec{F}_E = \rho_f \vec{E} - \frac{1}{2} |\vec{E}|^2 \nabla \epsilon + \nabla \left[\frac{1}{2} \rho \frac{\partial \epsilon}{\partial \rho} |\vec{E}|^2 \right]$$

$$\text{MQS: } \vec{F}_M = \vec{J}_f \times \vec{B} - \frac{1}{2} |\vec{H}|^2 \nabla \mu + \nabla \left[\frac{1}{2} \rho \frac{\partial \mu}{\partial \rho} |\vec{H}|^2 \right]$$